



IXARC Kit Encoder With BISS C Interface

- Kit Encoder for Integration to Motors, Robots and Machinery¹
- Electrical Resolution: Up To 17 bit
- Multiturn Range: Up To 32 Bit
- 36 mm Diameter
- Energy-Harvesting-System Based On Wiegand Effect
- No Battery No Maintenance
- Easy Installation with Self-Calibration

1. Interface

Interface	BiSS C
Programming Functions	Electronic Calibration, Counter Test
Min Interface Cylce Time	50 µs

2. Electrical Data

Supply Voltage	4.75-15 VDC
Power Consumption	≤ 0.3 Watt
Start-up time	Max 1 s
Clock Input	RS 422
Clock Frequency	100 kHz - 10 MHz
Reverse Polarity Protection	Yes
Short Circuit Protection	Yes
MTTF	20 years
Max. Permissible Electrical Speed	12.000 RPM

¹ The use of these kit encoders for the production of industrial rotary encoders is prohibited. Applications in rotary encoders are protected by several worldwide patents (such as WO 2004/046735 A1) and require licensing.



3. Sensor

Singleturn Technology	Magnetic
Electrical Resolution Singleturn	17 bit
Multiturn Technology	Self powered magnetic pulse counter (no battery, no gear)
Multiturn Range	16 bit
Accuracy (INL)	±0.0878° (≤ 12 bit)
Counting Direction (Default)	Clockwise shaft movement (front view on shaft)

4. Environmental Specifications

Operating Temperature	-40 °C (-40 °F) – +105 °C (221 °F)
Shock Resistance	≤ 200 g (half sine 6 ms, EN 60068-2-27)
Permanent Shock Resistance	≤ 20 g (half sine 16 ms, EN 60068-2-29)
Vibration Resistance	≤ 30 g (10 Hz – 1000 Hz, EN 60068-2-6)

5. Mechanical Data

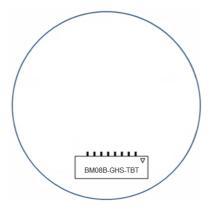
Housing Material	Steel
Housing Coating	Cathodic corrosion protection
Stator Type	POSITAL standard
Rotor Type	POSITAL standard
Max. Permissible Mechanical Speed	12,000 RPM

6. Electrical Connection

Connection Orientation	Axial
Connector	JST BM08B-GHS-TBT

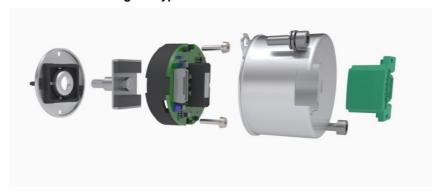


7. Connection Plan



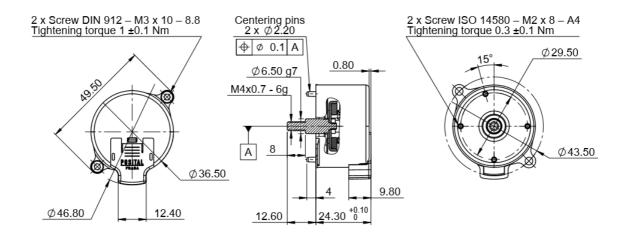
Pin	Signal
1	GND
2	Preset (default 0 position value)
3	Config (Kit Control box, serial communication)
4	Data + (SLO+)
5	Data - (SLO-)
6	CLK - (MA-)
7	CLK + (MA+)
8	VCC

8. Dimensional Drawing for Type KCD-BC01B-1617-U01C-xxx



This kit version contains 4 main parts to be assembled from left to right side: shielding, magnet, carrier with PCB and housing.



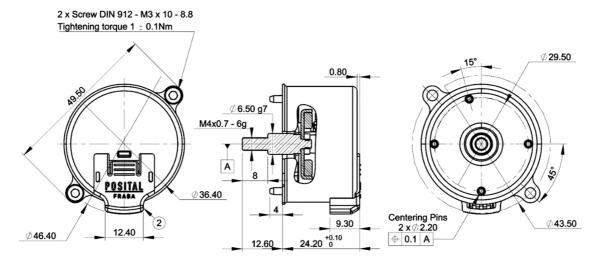


All dimension in [inch] mm. This drawing and the information contained is for general presentation purposes only. Please refer to the "Download" section for detailed technical drawings.

9. Dimensional Drawing for Type KCD-BC01B-1617-U01K-xxx



This kit version is quite easy to mount and contains 3 main parts to be assembled, from left to right side: shielding, magnet and housing with pre-assembled carrier inside.



All dimension in [inch] mm. This drawing and the information contained is for general presentation purposes only. Please refer to the "Download" section for detailed technical drawings.



10. Interface

Preset Pin

The preset function can be used to adapt the encoder position to the mechanical alignment of the system. By performing a preset, the actual position value of the encoder (both, singleturn and multiturn) is set to the desired preset value. The preset can be triggered via hardware or software. See manual for more detailed information.

Config Pin

The config pin is used for serial data communication. Via this interface an optional re-calibration and WIEGAND pulse testing of the kit encoder can be conducted after motor installation. A preset value can be applied as a software command. The protocol for communication is described in the manual. As alternative a graphical user interface with a Kit Control Box can be used for easy configuration and hardware setup, see website for more details.

https://www.posital.com/en/products/kit-encoders/kit-control-box.php

11. Version Space

KCD-BC01B-1617-U01K-JAQ* KCD-BC01B-1617-U01K-2RW* KCD-BC01B-1617-U01C-JAQ KCD-BC01B-1617-U01C-2RW 3-part assembly, PCB connector exit

3-part assembly, PCB connector and accessory 2 m PVC cable

4-part assembly, PCB connector exit

4-part assembly, PCB connector and accessory 2 m PVC cable

*Types recommended for new design.

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