

Manual AP23 Start/Stop Display



- 8 Digit display in DIN-enclosure 96 X 48 mm
- Supply voltage 10 – 35V DC
- All in- and outputs optically isolated
- Input for absolute Start-Stop sensors
- RS232
- 2 Digital inputs and 4 digital outputs
- 12 Programmable cams / 4 outputs
- 24 Programmable nominal values
- 12 Programmable Cams over 4 outputs
(cycle time 250µS)
- Programmable analog output (16 bit)
(with teach function)
- All connectors removable

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1 Introduction

1.1 General

With the microcontroller based AP23 it is possible to connect absolute sensors with Start-Stop interface (MTS Sensors)

It is standard equipped with 2 digital inputs and 4 digital outputs, all free programmable. The AP23 features a RS232 communication port and a analog output.

With the 12 programmable cams several functions can be realized like limit detection.

Another feature of the AP23 is the memory for the nominal values. The 24 programmable values can be used to determine the positions of the cams.

The microcontroller reads the actual sensor value and calculates the display-value and the actual velocity. A programmable power failure protection makes sure that the actual value is stored in an EEPROM. The AP23 is configurable for numerous applications by adjusting its parameters.

The AP23 can be programmed with the DST2 PC-based software.

1.2 *Important information*

- ✓ The AP23 is a high-tech electronic product. To ensure safety and a correct functioning of the product it is important that only qualified specialists will install and operate the AP23.
- ✓ If through a failure or fault of the AP23 an endangering of persons or damage to plant is possible, this must be prevented using additional safety measures. These must remain operational in all possible modes of the AP23.
- ✓ Necessary repairs to the AP23 are only to be carried out by the manufacturer.

1.3 *EMC*

To ensure the best possible electromagnetic compatibility, it is recommended to pay attention to shielding and grounding the AP23:

- ✓ Shielding on both sides and with the largest possible contact area.
- ✓ Keep wiring as short as possible.
- ✓ Earth-connections should be short and with the highest possible wiring-diameter.
- ✓ Signal-cables and supply-cables must be separated.
- ✓ The EMC-bracket type EMC-B02 should be used.

1.4 *Definitions*

1.4.1 *Display units AWE*

The display units, referred to as AWE, is the value shown on the display without regarding the decimal point. The decimal point is only used for the comfort of the operator, but has no functional meaning.
(display = 347.4 >> AWE = 3474)

1.4.2 *Parameter number*

A parameter number is always shown in the format P[xxx]. It is possible that a parameter number appears in more than one menu.

1.4.3 Notation

Values can be displayed in different notations like binary or hexadecimal. The character behind the value shows in which notation the value is represented:

100D	<u>D</u> ecimal
238H	<u>H</u> exadecimal
244G	<u>G</u> ray
10010011B	<u>B</u> inary

for example $220D = DCH = 11011100B$

1.4.4 Edges

- L → H : rising edge (low to high)
H → L : falling edge (high to low)

2 Operation

2.1 Key functions



[P] key

- Cycle through monitoring displays
- Activate programming mode (in combination with other keys)



[+1] key

- View type number



[Cursor] key

- View software version
- View custom software version (in combination with the [Enter] key)



[Enter] key

- View status of inputs and outputs

2.2 Key functions in programming mode



[P] key

- one step back in menu
- discontinue programming mode
- discontinue changing nominal values/parameters (edit mode)
- LED is on when programming mode is active



[+1] key

- cycle through menu
- increase nominal value- / parameter number
- increase digit (in edit mode)



[Cursor] key

- activate edit mode
- move one digit to the left (in edit mode)

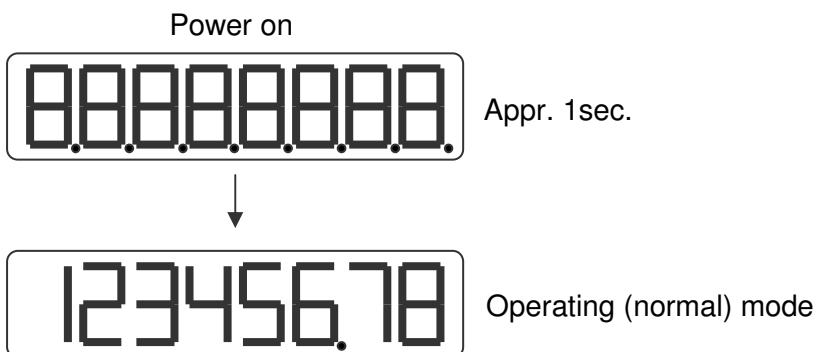


[Enter] key

- enter a submenu or parameter
- increase nominal value-/parameter number
- store a changed value
- clear value, hold down [Cursor] button (edit mode)

2.3 *Display functions*

2.3.1 *Status functions*

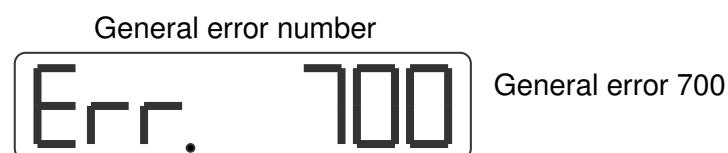


2.3.2 *Error messages*

There are two groups of errors:

- Parameter errors (error numbers 0...499, preceded by a “P”)
- General error (error numbers from 500 and up)

Example:



2.3.3 Survey of error messages

Error no:

000...499 Parameter error is displayed as PXXX on the display.

716 = Umin >= Umax (analog output)

717 = Imin >= Imax (analog output)

720 = Changelock nominal values active

721 = Changelock parameters active

732 = Function input-2 not valid (equal to input-1)

810 = Start/Stop error no magnet detected

811 = Start/Stop error time-out no stop signal detected

Error messages for cams (last 2 digits = cam number)

10xx

Counting range active

Length cam = 0 (if counting range is active)

No counting range active or source for cam is velocity

Length cam <= 0

11xx Length cam <= Hysteresis

12xx Hysteresis too large or length cam too large (2 * Hysteresis) + Length

>= Counting range

13xx cam begin and/or cam end outside counting range (incl. hysteresis)

Error messages ASCII

er 1 = parity error

er 2 = frame error

er 3 = overflow error

er 4 = buffer overrun

er 5 = number invalid

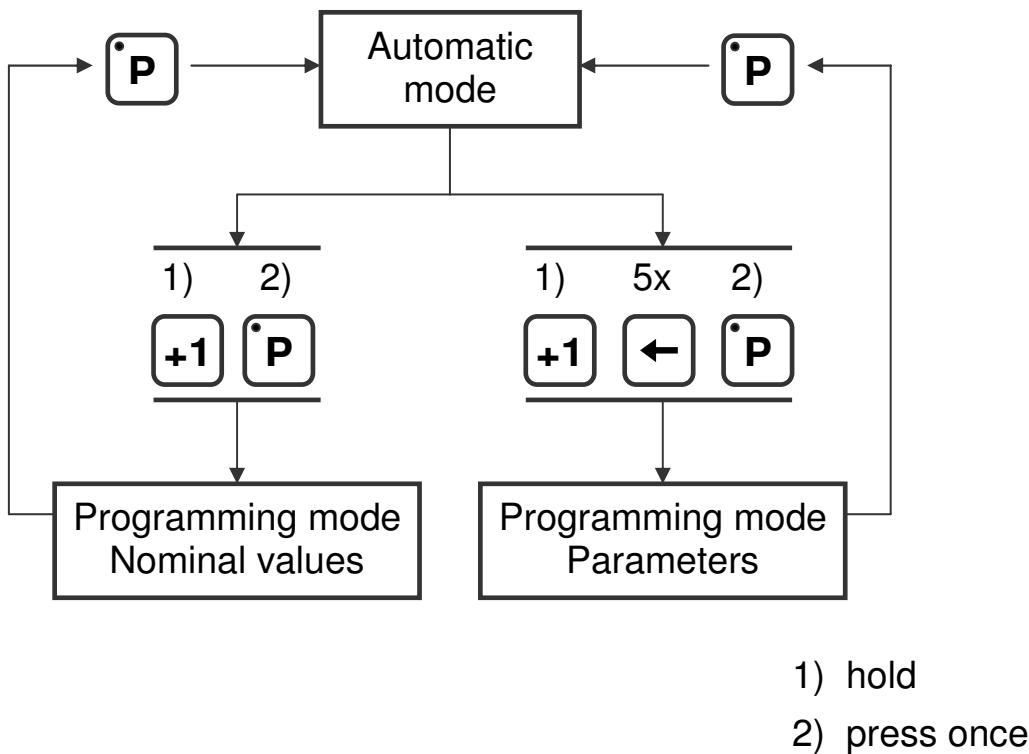
er 6 = data invalid (outside min/max value)

er 7 = programming mode parameters/nominal values active

3 Programming

There are three different modes of operation:

- Automatic mode
- Programming mode for nominal values
- Programming mode for parameters



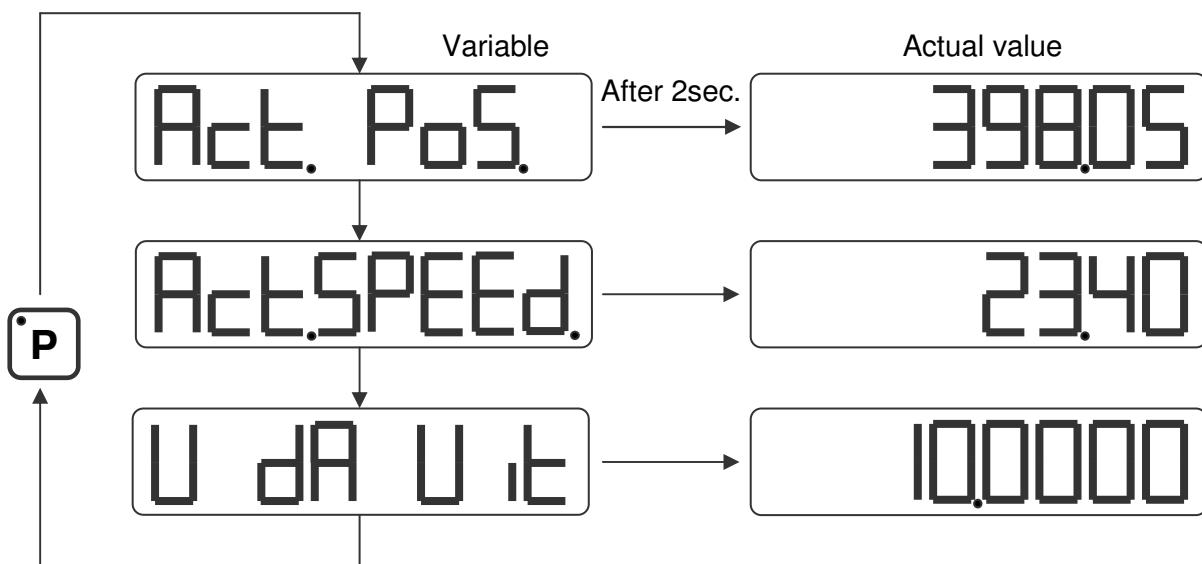
3.1 Automatic mode

In the automatic mode, depending on the type of sensor, the increments are counted or the absolute position is read and the result is shown on the display as the actual value. The velocity is calculated and can be visualized as well.

3.1.1 Monitor function

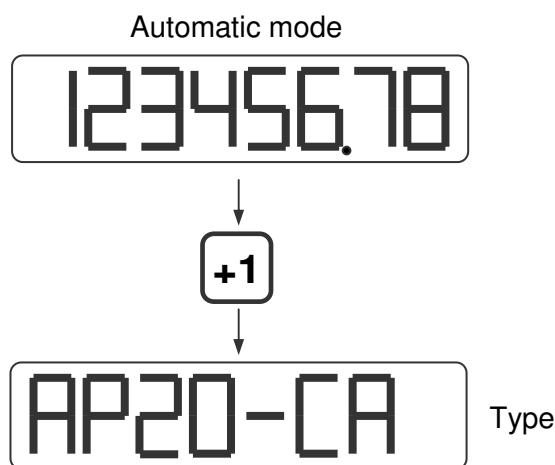
In automatic mode different variables can be displayed. By using the [P] key one can cycle through the different pages:

- Actual position
- Actual velocity
- Voltage or current of the DA (analog out)

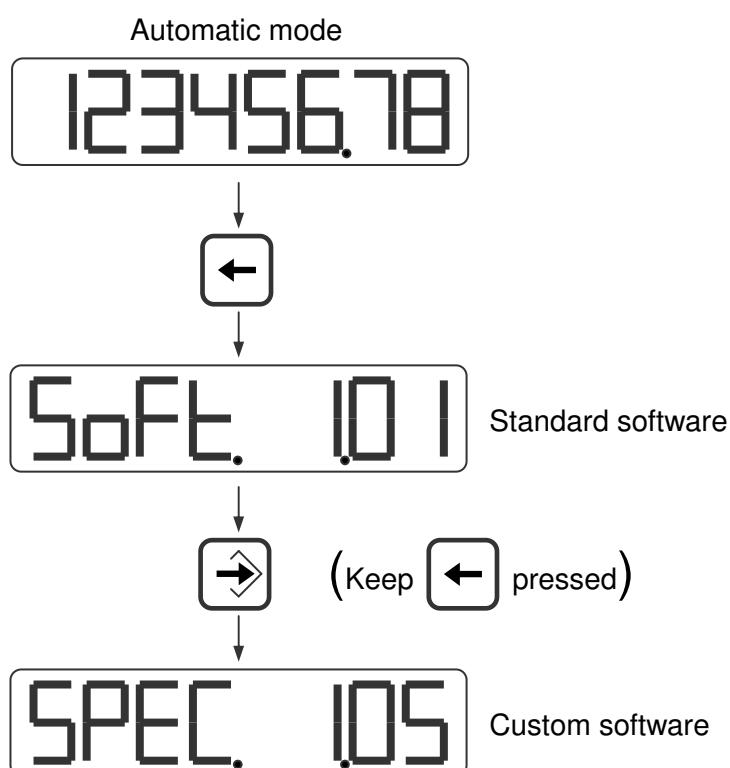


Parameter P[208] determines which option is visible after start-up.

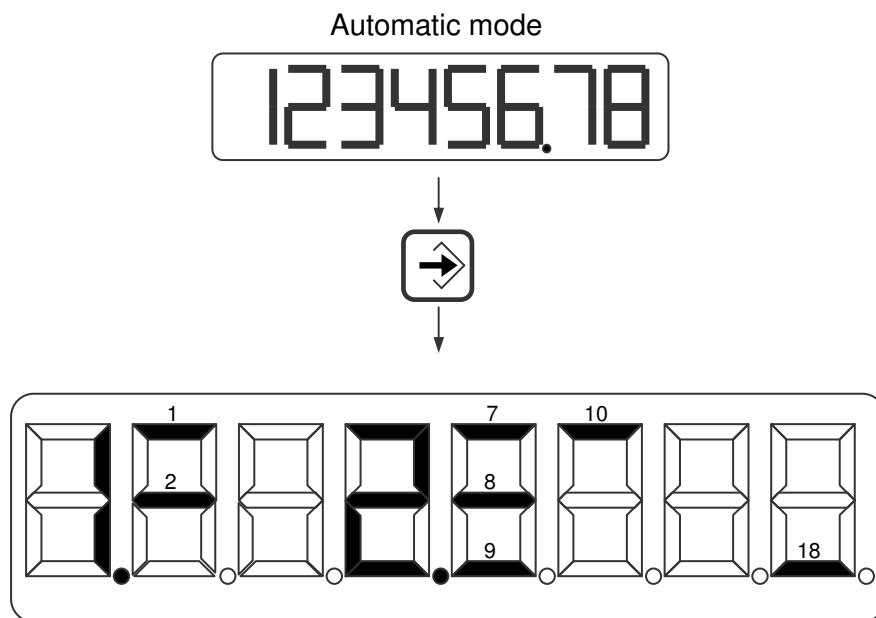
3.1.2 *Displaying the type number*



3.1.3 *Displaying the software-version*



3.1.4 Status in- and outputs



Inputs

1 = input-1
2 = input-2

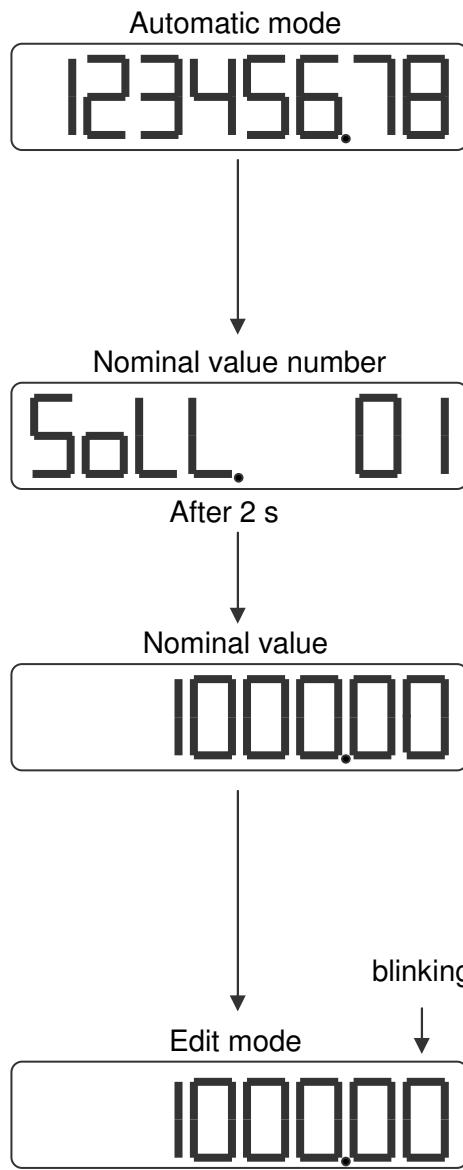
Outputs

7 = output-1
8 = output -2
9 = output -3
10 = output -4

Outputs

18 = Cams active

3.2 *Changing nominal values*



Access to nominal values

*) Then **+1** **P**

Select nominal values

- P** Exit programming mode
- +1** Nominal value number +1
- ←** Activate edit mode
- Nominal value number +1

Changing values

- P** Exit edit mode
- +1** Increase digit
- ←** Move one digit left
- Confirm change
- *) Then **←** **→** Clear input

*) keep pressed

3.3 *Changing parameters*

3.3.1 *Menus*

The parameters are displayed in different menus and submenus:

1 ConFiG

2 ActuAL

3 SEriAL

4 InPut

5 OutPut

6 Cam

 6.1 CA1

 6.12 CA12

7 An out

 7.1 ConFG.

 7.2 dA-U

 7.3 dA-I

Example:

*PAr. 6.1.1 means
menu 6, submenu 1, parameter 1*

Manual AP23 Start/Stop Display

2010 V02. For software version V2.00. Subject to change without notice.

DIECON

3.3.2 Input parameters

Automatic mode

123456.78

↓
Menu

I Conf G

↑
Menu

Submenu

2. I Cnt.

↑
Menu

↑ submenu

Parameter number

P 2. | |

After 2s

↑
Menu

↑ submenu

↑ Par.

Parameter value

100000

blinking

↓
Edit mode

100000.

*) keep pressed down

Access parameters

*)
+1

5x
← Then P

Menu selection

• P

Exit programming mode

+1

Menu item +1

→

To submenu/parameter number

Submenu selection

• P

Back to menu

+1

Submenu item +1

→

To parameter number

Selecting parameters

• P

Back to menu/submenu

+1

Parameter number +1

←

Activate edit mode

→

Parameter number +1

Changing parameters

• P

Exit edit mode

+1

Increase digit-value

←

Move 1 digit to the left

→

Confirm input

*)
←

Then → Clear input

4 Functions

4.1 Actual position

The actual position shown on the display.

$$\text{Actual position} = \text{Sensor} \times \text{dir} \times \frac{\text{Mt}}{\text{Mn}} + \text{N}$$

Mt	= multiplicator numerator	P[000]
Mn	= multiplicator denominator	P[001]
N	= offset	P[002]
dir	= direction (x1 or x -1)	P[211]

4.2 Velocity measurement

The velocity measurement is always active and delivers the actual speed in AWE/s.

Two parameters are necessary to configure the measurement:

P[088] = measuring time [AWE/s]

The smaller the measurement time the more dynamic the velocity measurement will be. This time is also the refreshment-interval on the display.

P[202] = integrator

The number of cycles are programmed. The average velocity (unit =AWE/s) of the programmed cycles is calculated.

Example:

Measurement time = 50ms, integrator = 10.

The actual velocity will be refreshed every 50 ms and is the average velocity during the last 10 measurements.

4.3 Gradient

Every sensor has it's own characteristic internal sensor speed. This speed is defined as gradient in m/s. for example 2789,00 m/s.

For MTS sensors this gradient is written on the type shield.

The gradient value can be programmed as Parameter P[115] in the AP23.

The measurement position will then be displayed correctly.

Parameter "Sensor length" P[118] can be set to the nominal sensor length so the AP23 can calculate the number of measurements per second.

4.4 Justage

The justage of absolute sensors can be done in 4 ways:

- Using the parameter "Adjustment absolute value" P[005]
- Using the input input 1 or 2)
- Using parameter service functions P[207]
- Using keys

4.4.1 Preset using the parameter "Adjustment absolute value"

This function is applicable for absolute sensors and is active when parameter "Adjustment" P[218] has been set to: "3 PAR"

Parameter "Adjustment absolute value" P[005] can be set to a value to adjust the encoder. This value (which can be negative and positive) will be added to the actual value.

4.4.2 Using the input (input 1 or 2)

In this function the actual position can be preset to a certain value. The function is active when parameter "adjustment" P[218] is set to one of the following options:

option: "1 L→H Input RAM"	(rising edge input)
option: "2 H→L Input RAM"	(falling edge input)
option: "4 L→H Input EEPROM"	(rising edge input)

Parameter "adjustment value" P[005] can be set to a value to which the actual position will be adjusted when input 1 or 2 detects a rising edge, possibly combined with a reference coarse signal ([P213]).

If through parameter [P213] reference coarse has been activated ([P213] <> 0), the option "1 - Reference coarse" should be selected for one of the inputs 1...2 (P[249]...P[250]).

The calculated offset will be stored in either RAM or EEPROM depending on the option chosen in parameter "adjustment" P[218]. When storing into RAM-memory (option 1 and 2) this will occur on a interrupt basis and can be per-

formed during movement. The memory however is volatile and the value will not be permanently stored.

Storing the value into EEPROM (option 4) is not initiated by an interrupt. It is recommendable to perform this only when not moving or moving very slow. This value will be stored permanently.

4.4.3 *Using service parameter P[207]*

When P[207] has the value 111 then the actual position is adjusted to the value of P[005] when the programming mode is left.

After executing this function parameter P[207] will have the value 0 again.

4.4.4 *Justage using keys*

The function preset the absolute position can be executed with the key combination [Enter] + [P].

Holding down the [Enter] key and push the [P] button once. Then the actual position is preset to the value of P[005].

This function is active when: P[218] = variant "5 keys"

4.5 ASCII protocol

The serial port of the AP23 is able to work with an ASCII protocol.

Using the ASCII protocol, actual values can be read, parameters and nominal values can be stored and read, the status of the digital inputs and outputs can be monitored etc.

4.5.1 Overview functions

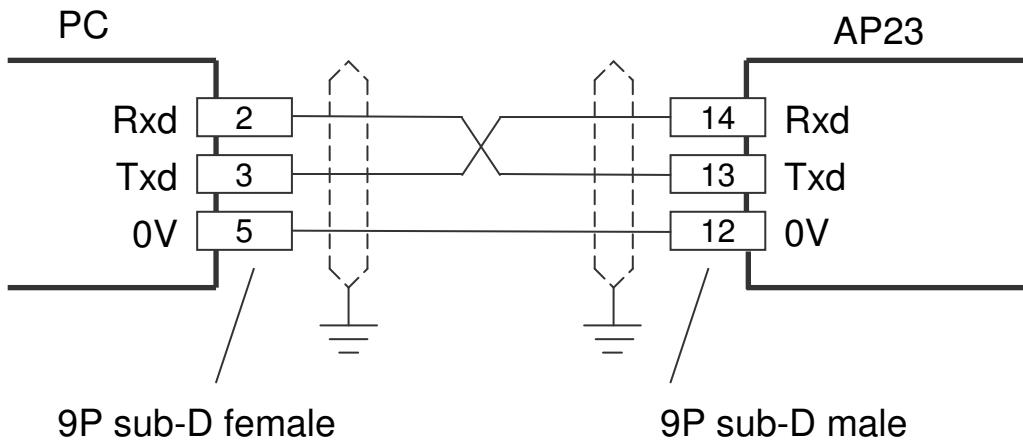
- sc** **select AP23**
- r0** **Read actual position (AWE)**
- r1** **Read actual velocity (AWE/s)**
- r2** **Read actual voltage analog output (0,1mV units)**
- r3** **Read actual current analog output (0,1 mA units)**
- ri** **Read status inputs**
- ru** **Read status outputs**
- wu** **Write outputs**
- rp** **Read parameter**
- wp** **Write parameter (Only EEPROM)**
- rs** **Read nominal value**
- ws** **Write nominal value (RAM + EEPROM)**
- rx** **Read software version**
- rt** **Read type number**
- rh** **Read hardware version**
- rf** **Read error number**
- wf** **Reset SSI error**
- rn** **Read status bits**
- bp** **Load and activate**

4.5.2 General

Through the ASCII protocol it is possible to communicate with the AP23.

Send: Data from PC, PLC → AP23

Receive: Data from AP23 → PC, PLC



Send structure:

Functioncode (space) [argument 1](space)[argument 2] <CR>

Receive structure:

Functioncode (space) [argument1](space)[argument 2] <CR> <LF>

Functioncode (space) [argument1] [argument 2].

Argument 1 and 2 are depending on the function and are separated by a space.

Example:

wp 20 250 (write value 250 to parameter 20)

4.5.3 Functions

sc Select AP23

send: **sc xx**
receive: **sc xx**
transmitting parameter: Unit Id number

The AP23 with the unit Id number is selected, all consecutive commands are relevant for this unit.

An AP23 with unit Id number 1 will always respond.

r0 Read actual position (AWE)

send: **r0**
receive: **r0 xxxxxxxx**
transmitting parameter: none

r1 Read actual velocity (AWE/s)

send: **r1**
receive: **r1 xxxxxxxx**
transmitting parameter: none

r2 Read actual voltage analog output (0,1mV units)

send: **r2**
receive: **r2 xxxxxxxx**
transmitting parameter: none

r3 Read actual current analog output (0,1 mA units)

send: **r3**
receive: **r3 xxxxxxxx**
transmitting parameter: none

ri Read status inputs

send: **ri**
receive: **ri xxx**
transmitting parameter: none

B0 = input-1
B1 = input-2
B2 = 0
B3 = 0
B4 = 0
B5 = 0
B6 = 0
B7 = 0

Example: ri 03 gives the following answer:

03 → 03H, 0000 0011 B
input-1 = "1"
input-2 = "1"

ru Read status outputs

send: **ru**
receive: **ru xxx**
transmitting parameter: none

B0 = output-1
B1 = output-2
B2 = output-3
B3 = output-4

wu Write outputs

(only valid for outputs with “ASCII protocol” selected)

send: **wu xxx**
receive: **wu xxx**
transmitting parameter: data for output

B0 = output-1
B1 = output-2

Example:

Output-2 should be set to “1”:

00000010B = 02H = 02D

send: wu 10

receive: wu 10

rp Read parameter

send: rp xxx

receive: rp xxxxxxxx

transmitting parameter : parameter number

Example reading parameter P[004]

send: rp 4

answer: rp 4 10000

wp write parameter (only EEPROM)

send: wp xxx xxxxxxxx

receive: wp xxx xxxxxxxx

transmitting parameter: parameter number and parameter value

Example writing parameter P[004] with value 185000

send: wp 4 185000

answer: wp 4 185000

Parameter will be stored to EEPROM but is not yet active.

rs Read nominal value

send: rs xx

receive: rs xx xxxxxxxx

transmitting parameter: nominal value

Example reading nominal value 22

send: rs 22

answer: rs 22 72500

ws Write nominal value (RAM + EEPROM)

send: **ws xx xxxxxxxx**
receive: **ws xx xxxxxxxx**
transmitting parameter: nominal value number and nominal value

Example writing nominal value 22 with value 195200

*send: wp 22 195200
answer: wp 22 195200*

rx Read software version

send: **rx**
receive: **rx SW Vxx.xx SSW xx.xx**
transmitting parameter: none

SW = standard software version
SSW = special software version

Example:

*send: rx
answer: rx SW 4.02 SSW 1.00*

rt Read type number

send: **rt**
receive: **rt AP23-DA**
transmitting parameter: none

Example:

*send: rt
answer: rt AP23-DA*

rh Read hardware version

send: **rh**
receive: **rh HW x RV x**
transmitting parameter: none

rf Read error number

send: **rf**
receive: **rf xxxx**
transmitting parameter: none

When -1 returns no error is present.

Example:

send: **rf**
answer: **rf 004** (parameter error)
or
answer: **rf -1** (no error)

wf Reset SSI error

send: **wf**
receive: **wf**
transmitting parameter: none

rn Read status bits

send: **rn**
receive: **rn xxx**
transmitting parameter: none

B0 = cams active (started)
B1 = reference set

bp Load and activate

send: **bp**
receive: **bp xxx**
transmitting parameter: none

In case of an error the error number will be returned (-1 is no errors).

Example: answer: **bp -1** (no errors)
answer: **bp 20** (error parameter 20)

4.5.4 Error messages

In case of an error the AP23 will sent an error message followed by an error number.

overview error messages

- er 1** = parity error
- er 2** = frame error
- er 3** = overflow error
- er 4** = buffer overrun
- er 5** = number invalid
- er 6** = data invalid (for example outside min/max range)
- er 7** = programming mode parameters/nominal values still active
- er 8** = function impossible

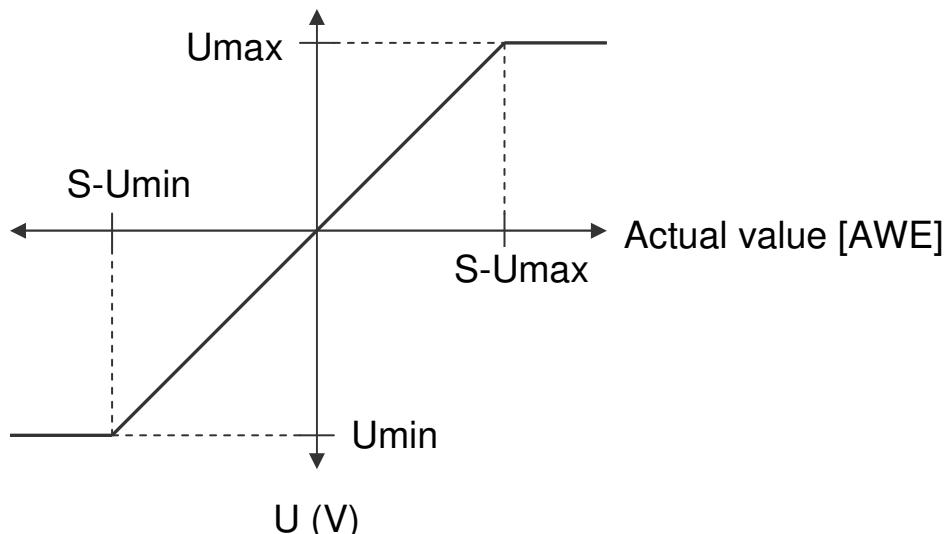
4.6 Analog output

The AP23 has an optional, galvanically isolated analog output. Using parameter P[231] it is possible to choose between a current output or a voltage output. The analog output can be used to give out the actual position or velocity (see parameter P[230]).

4.6.1 Voltage output

The voltage output has a resolution of 305 µV and is programmable through P[080] ... P[083].

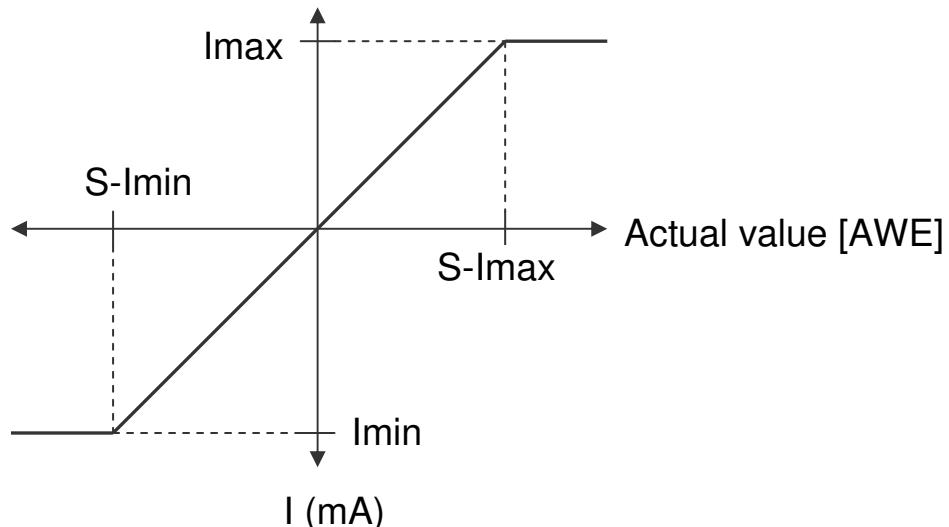
- P[080] = Umin [V] (input in 0,0001V units)
- P[081] = Umax [V] (input in 0,0001V units)
- P[082] = S-Umin [AWE] (actual value at Umin)
- P[083] = S-Umax [AWE] (actual value at Umax)



4.6.2 Current output

The current output has a resolution of 610 μ A and is programmable through P[084] ... P[087].

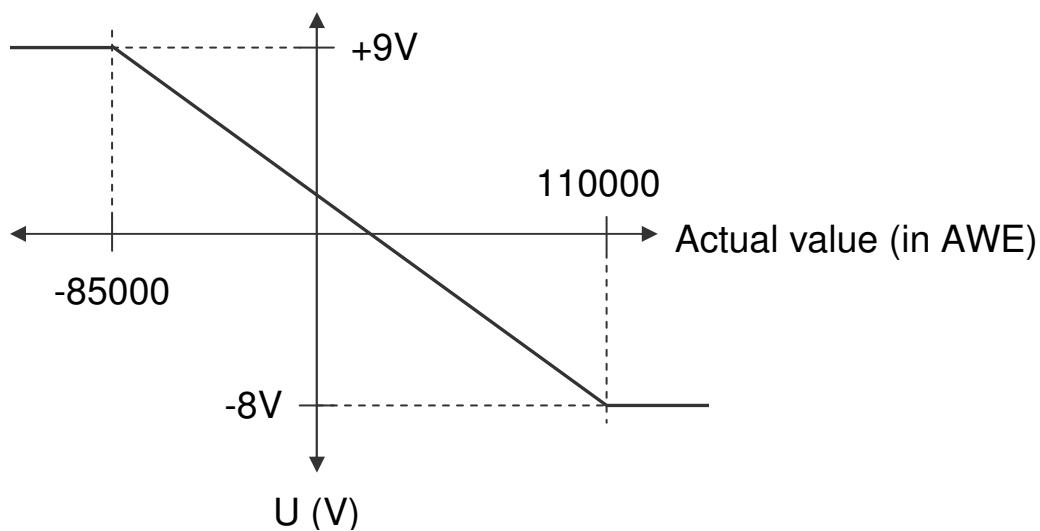
- P[084] = Imin [A] (input in 0,0001mA units)
- P[085] = Imax [A] (input in 0,0001mA units)
- P[086] = S-Imin [AWE] (actual value at Imin)
- P[087] = S-Imax [AWE] (actual value at Imax)



4.6.3 Example programming voltage output

- > 0,01 mm units
- > actual position at +9V should be -850,00 mm
- > actual position at -8V should be 1100,00 mm

P[080]	= Umin	= -8,0000 [V]
P[081]	= Umax	= +9,0000 [V]
P[082]	= S-Umin	= 110000 [AWE]
P[083]	= S-Umax	= -85000 [AWE]



4.7 Teach function analog output

The value for Smin and Smax can be set by an external input signal. For this function parameter P[234] and or P[235] can be set to variant "1 Teach via input". The function for the input 1...4 can be set to variant "11 DAC Set Smin" or variant "12 DAC Set Smax".

On the positive edge of the input signal the teach function will be executed. The value of Smin or Smax will be stored with de actual position or the actual speed depending on parameter P[230]. The display will show "teach Lo" or "teach hi" for a short time.

4.8 Cams

4.8.1 General

The AP23 has a maximum of 12 programmable cams divided over a maximum of 4 outputs.

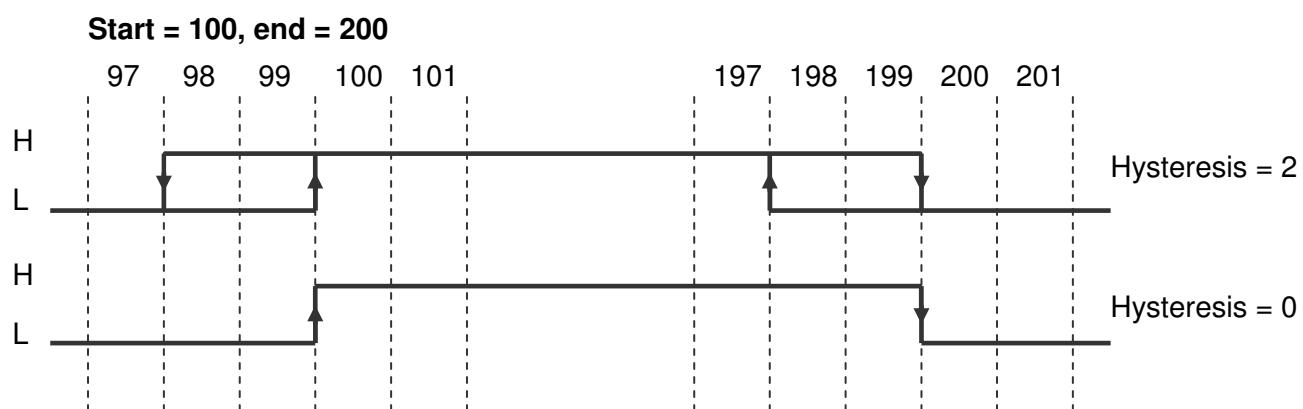
Programmable functions:

- Type
 1. Cam with start- and end-value
 2. Greater than or equal to limit value
 3. Smaller than or equal to limit value
- Source (actual position or actual velocity)
- Nominal value location number for start-, end-, or limit value
- Hysteresis
- Output for cam

Per cam one can choose whether to program the values directly into the parameters or to use a nominal value location number where the values are programmed.

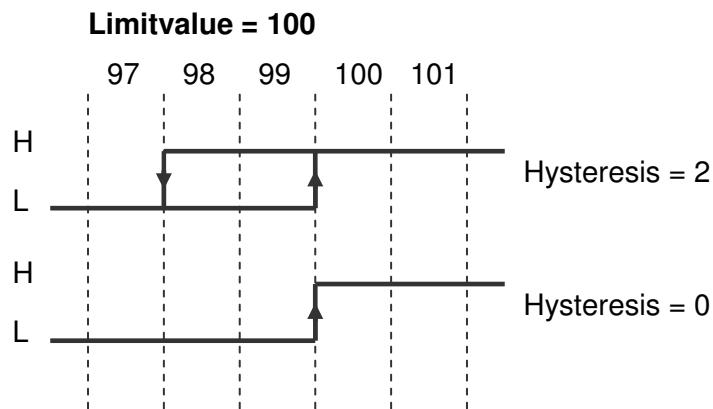
4.8.2 Cam with start- and end-value

Two values are programmed, a start value and an end-value.



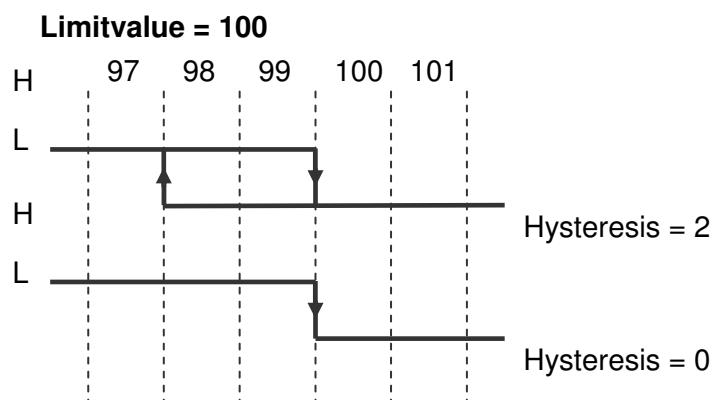
4.8.3 *Greater than or equal to limit value*

Only one limit value needs to be programmed.



4.8.4 *Smaller than or equal to limit value*

Only one limit value needs to be programmed.



4.8.5 *Start/stop cam*

The outputs for the cams can be enabled or disabled. If for one of the inputs 1..6 the function start/stop cams has been chosen.

Start/stop cams with one signal

Input-x = option "**5 start/stop cams**" (high = cams enabled)

Start/stop cams with double signal

Input-x = option "**6 start cams**" (rising edge = enable cams)

Input-x = option "**7 stop cams**" (rising edge = disable cams)

4.8.6 *Output "Cams active"*

On one of the outputs 1...4 the signal "cams active" can be generated by choosing option "**4 cams active**" (high = cams enabled).

5 Parameters

General lay-out:

PAR.	PAR Nr:	Possible values (bold is the standard value)
Basic description		
Description of possible values		

5.1 Menu 1 Config

PAR: 1.0.1	P[088]	0 ... 40 ... 2500
Measuring time velocity [AWE/s] (equal to refreshment time display) X.XXX (sec) input 0 .. 1.000s		

PAR: 1.0.2	P[202]	0 ... 10 ... 20
Integrator velocity Actual velocity is the average from the number of measurements		
0 = not active		
1...20 number of measurements		

PAR: 1.0.3	P[203]	0 ... 6
Number of decimals		
X		

PAR: 1.0.4	P[204]	0 ... 1
Store function		
0 = no function		
1 = display		

PAR: 1.0.5	P[205]	0 ... 2
Store signal		
0 = high active		
1 = low active		

PAR: 1.0.6	P[206]	0 ... 1
Power failure protection (only AP20)		
0 = not active		
1 = active		

Manual AP23 Start/Stop Display

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PAR: 1.0.7	P[207]	0 ... 123
Service functions		
Only possible to activate through keyboard AP23		
Value is automatically set to 0 after executing the service function		
0 = not active		
123 = set default parameters		
111 = adjusting absolute sensors or preset function counter and freq.		

PAR: 1.0.8	P[208]	0 ... 1
Default monitor function		
Determines the default which is visible after start-up.		
0 = Actual position		
1 = Actual velocity		

Manual AP23 Start/Stop Display

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5.2 Menu 2 Actual

PAR: 2.4.1	P[115]	0 ... 280000 .. 999999
Gradient		
Actual signalspeed sensor internal in m/s (0 = 2800.00 m/s)		
XXXX.XX (m/s)		

PAR: 2.4.2	P[118]	0 ... 6000 ... 29999
Measuring length sensor		
XXXXX mm		

PAR: 2.4.3	P[211]	0 ... 1
Counting direction		
0 = no reverse		
1 = reverse		

PAR: 2.4.4	P[000]	0 ... 10000 ... 16777215
Multiplicator numerator		
XXXXXXX		

PAR: 2.4.5	P[001]	0 ... 10000 ... 16777215
Multiplicator denominator		
XXXXXXX		

PAR: 2.4.6	P[219]	0 ... 5
Adjustment		
0 = no function		
1 = rising edge (input) only temporary in RAM (on interrupt)		
2 = falling edge (input) only temporary in RAM (on interrupt)		
3 = set with parameter adjustment value		
4 = rising edge (input) permanent in EEPROM (not on interrupt)		
5 = keys		

PAR: 2.4.7	P[213]	0 ... 2
Reference coarse		
0 = no function		
1 = high signal		
2 = low signal		

Manual AP23 Start/Stop Display

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PAR: 2.4.8	P[209]	0 ... 2
------------	--------	----------------

Counting direction adjustment

0 = independant from direction

1 = when counting in positive direction

2 = when counting in negative direction

PAR: 2.4.10	P[002]	-9999999 ... 0 ... 99999999
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Offset

-XXXXXXXX (AWE)

PAR: 2.4.11	P[005]	-9999999 ... 0 ... 99999999
-------------	--------	------------------------------------

Adjustment value

-XXXXXXXX (AWE) input 0 means function inactive

5.3 Menu 4 Serial

PAR: 3.0.1	P[236]	0 ... 31
Unit adress		
XX		

PAR: 3.0.2	P[237]	0 ... 1 ... 4
Baudrate		
0 = 9600		
1 = 19200		
2 = 28800		
3 = 38400		
4 = 57600		

PAR: 3.0.3	P[238]	0 ... 1
Number of stopbits		
0 = 1 Stopbit		
1 = 2 Stopbits		

PAR: 3.0.4	P[239]	0 ... 2
Parity		
0 = none		
1 = odd		
2 = even		

PAR: 3.0.5	P[240]	0 ... 1
Protocol		
0 = no function		
1 = ASCII		

5.4 Menu 5 Input

INPUT-1

PAR: 4.0.1	P[249]	0 ... 12
Function input-1		
0	= no function	
1	= coarse	
2	= reference fine	
3	= store	
4	= error reset SSI	
5	= start/stop cams	
6	= start cams	
7	= stop cams	
8	= lock input nominal values	
9	= lock input parameters	
10	= lock input nominal values + parameters	
11	= DAC Set Smin	
12	= DAC Set Smax	

INPUT-2

PAR: 4.0.2	P[250]	0 ... 12
Function input-2		
XX	(see input-1)	

Manual AP23 Start/Stop Display

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5.5 Menu 6 Output

OUTPUT 1

PAR: 5.0.1	P[252]	0 ... 7
Function output-1		
0	= cam	
1	= cam inverted	
2	= SSI error (high = no error) only AP21	
3	= Start/Stop error (no magnet or time-out) only AP23	
4	= reference/adjustment set	
5	= cams active	
6	= ASCII protocol	
7	= Counting direction (high = downwards counting)	

OUTPUT-2

PAR: 5.0.2	P[253]	0 ... 7
Function output-2		
XX (see output-1)		

OUTPUT-3

PAR: 5.0.3	P[254]	0 ... 7
Function output-3		
XX (see output-1)		

OUTPUT-4

PAR: 5.0.4	P[255]	0 ... 7
Function output-4		
XX (see output-1)		

5.6 Menu 6 Cam

5.6.1 Submenu 9.1 ... 9.12 CA1...12

CAM-1...12

PAR: 6.x.1	P[256]...P[267]	0 ... 3
Cam function		
0 = no function		
1 = range		
2 = actual position >= limit value		
3 = actual position <= limit value		

PAR: 6.x.2	P[280]...P[291]	0 ... 1
Source		
0 = actual position		
1 = actual velocity		

PAR: 6.x.3	P[304]...P[315]	0 ... 12
Source cam begin / limit value (limit value if cam function = 2 or 3)		
0 = parameters cam begin		
1...12 = Nominal value 1...12		

PAR: 6.x.4	P[292]...P[303]	0 ... 12
Source cam end		
0 = parameters cam end		
1...12 = Nominal value 1...12		

PAR: 6.x.5	P[007]...P[018]	-9999999 ... 1000 ... 99999999
Cam begin / limit value (limit value if cam function = 2 or 3)		
-XXXXXXX		

PAR: 6.x.6	P[031]...P[042]	-9999999 ... 2000 ... 99999999
Cam end		
-XXXXXXX		

PAR: 6.x.7	P[055]...P[066]	0 ... 999999
Hysteresis cam		
XXXXXX		

Manual AP23 Start/Stop Display

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PAR: 6.x.8	P[268]...P[279]	0 ... 4
------------	-----------------	----------------

Assign cam to output

0 = no output

1...4 = output 1-4

5.7 Menu 7 Analog output

5.7.1 Submenu 7.1 Config

PAR: 7.1.1	P[231]	0 ... 2
------------	--------	----------------

Selection DA output

0 = inactive

1 = voltage

2 = current

PAR: 7.1.2	P[230]	0 ... 1
------------	--------	----------------

Selection DA source

0 = actual position

1 = actual velocity

5.7.2 Submenu 7.2 DA-U (voltage)

DA PAR 7.2.1...7.2.4 = 0: DA not active

PAR: 7.2.1	P[080]	-100000 ... 99999
------------	--------	--------------------------

Umin DA

-XX.XXXX (V)

PAR: 7.2.2	P[081]	-99999 ... 100000
------------	--------	--------------------------

Umax DA

-XX.XXXX (V)

PAR: 7.2.3	P[082]	-9999999 ... -100000 ... 99999999
------------	--------	------------------------------------------

S-Umin DA

-XXXXXXXX (AWE)

PAR: 7.2.4	P[083]	-9999999 ... 100000 ... 99999999
------------	--------	-----------------------------------------

S-Umax DA

-XXXXXXXX (AWE)

Manual AP23 Start/Stop Display

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PAR: 7.2.5	P[234]	0 ... 1
------------	--------	----------------

Source for Smin

0 = parameter Smin

1 = teach by input

PAR: 7.2.6	P[235]	0 ... 1
------------	--------	----------------

Source for Smax

0 = parameter Smax

1 = teach by input

5.7.3 Submenu 8.3 DA-I (current)

DA PAR 7.2.1...7.2.4 = 0: DA not active

PAR: 7.3.1	P[084]	-200000 ... 199999
------------	--------	---------------------------

Imin DA

-XX.XXXX (mA)

PAR: 7.3.2	P[085]	-199999 ... 200000
------------	--------	---------------------------

Imax DA

-XX.XXXX (mA)

PAR: 7.3.3	P[086]	-9999999 ... -200000 ... 99999999
------------	--------	------------------------------------------

S-Imin DA

-XXXXXXXX (AWE)

PAR: 7.3.4	P[087]	-9999999 ... 200000 ... 99999999
------------	--------	-----------------------------------------

S-Imax DA

-XXXXXXXX (AWE)

PAR: 8.3.5	P[234]	0 ... 1
------------	--------	----------------

Source for Smin

0 = parameter Smin

1 = teach by input

PAR: 7.3.6	P[235]	0 ... 1
------------	--------	----------------

Source for Smax

0 = parameter Smax

1 = teach by input

5.8 Overview parameters

No	Description	Menu
[000]	= Multiplicator numerator	2.4.4
[001]	= Multiplicator denominator	2.4.5
[002]	= Offset	2.4.9
[003], [004]	= no function	
[005]	= Adjustment absolute value	2.4.10
[006]	= Delta-SSI monitoring per cycle	2.2.12
[007]...[018]	= Cam begin / limit value	6.1.5...6.12.5
[019]...[030]	= no function	
[031]...[042]	= Cam end	6.1.6...6.12.6
[043]...[054]	= no function	
[055]...[066]	= Hysteresis cam	6.1.7...6.12.7
[067]...[079]	= no function	
[080]	= Umin DA	7.2.1
[081]	= Umax DA	7.2.2
[082]	= S-Umin DA	7.2.3
[083]	= S-Umax DA	7.2.4
[084]	= Imin DA	7.3.1
[085]	= Imax DA	7.3.2
[086]	= S-Imin DA	7.3.3
[087]	= S-Imax DA	7.3.4
[088]	= Measuring time velocity	1.0.1
[089]...[114]	= no function	
[115]	= gradient Start/Stop sensor	2.4.1
[116], [117]	= no function	
[118]	= measuring length Start/Stop sensor	2.4.2
[119]...[201]	= no function	
[202]	= Integrator velocity	1.0.2
[203]	= Number of decimals	1.0.3
[204]	= Store function	1.0.4
[205]	= Store signal	1.0.5
[206]	= Power failure protection	1.0.6
[207]	= Service functions	1.0.7
[208]	= Default monitor function	1.0.8
[209]	= Counting direction for justage	2.4.8
[210]	= no function	
[211]	= Counting direction	2.4.3
[212]	= no function	
[213]	= Reference coarse	2.4.7
[214]...[217]	= no function	

Manual AP23 Start/Stop Display

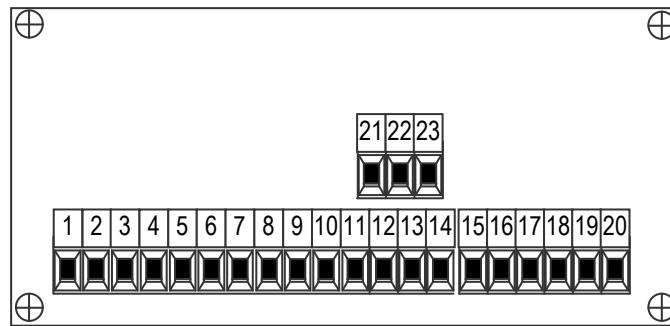
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No	Description	Menu
[218]	= adjustment	2.4.6
[219]...[229]	= no function	
[230]	= Selection DA source	1.1.2
[231]	= Selection DA output	7.1.1
[232], [233]	= no function	
[234]	= Source for Smin DA	7.2.5/7.3.5
[235]	= Source for Smax DA	7.2.6/7.3.6
[236]	= Unit address	3.0.1
[237]	= Baudrate (RS232)	3.0.2
[238]	= Stopbits (RS232)	3.0.3
[239]	= Parity (RS232)	3.0.4
[240]	= Protocol (RS232)	3.0.5
[241]...[248]	= no function	
[249], [250]	= Function input 1...2	4.0.1/4.0.2
[251]	= no function	
[252]...[255]	= Function output1...4	5.0.1...5.0.4
[256]...[267]	= Camfunction	6.1.1...6.12.1
[268]...[279]	= assign cam to output	6.1.8...6.12.8
[280]...[291]	= Source cam	6.1.2...6.12.2
[292]...[393]	= Source for cam end	6.1.4...6.12.4
[304]...[315]	= Source for cam begin/limit value	6.1.3...6.12.3
[316]...[399]	= no function	

6 Connections

Connections on the rear

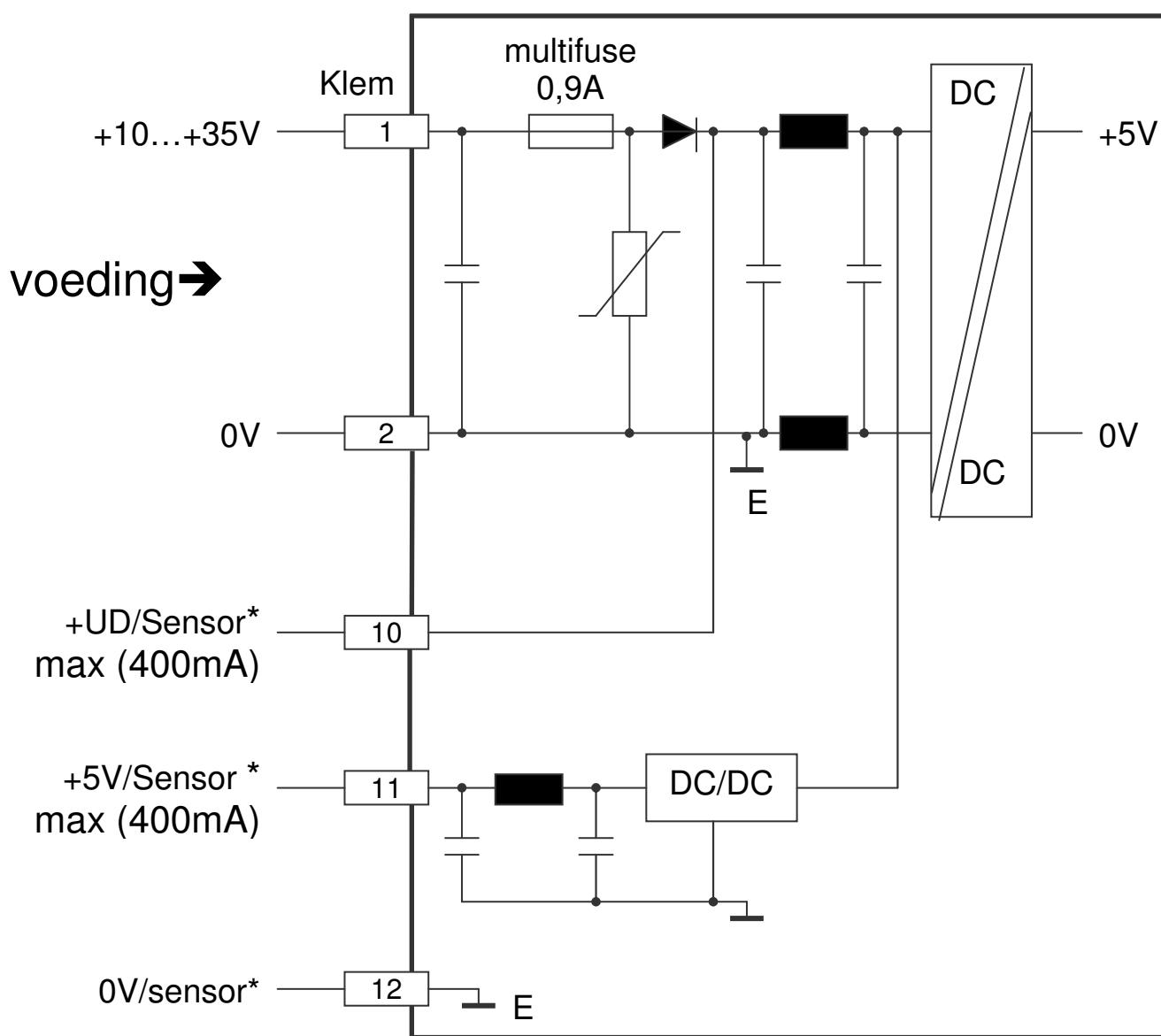


6.1 Overview clamp connections

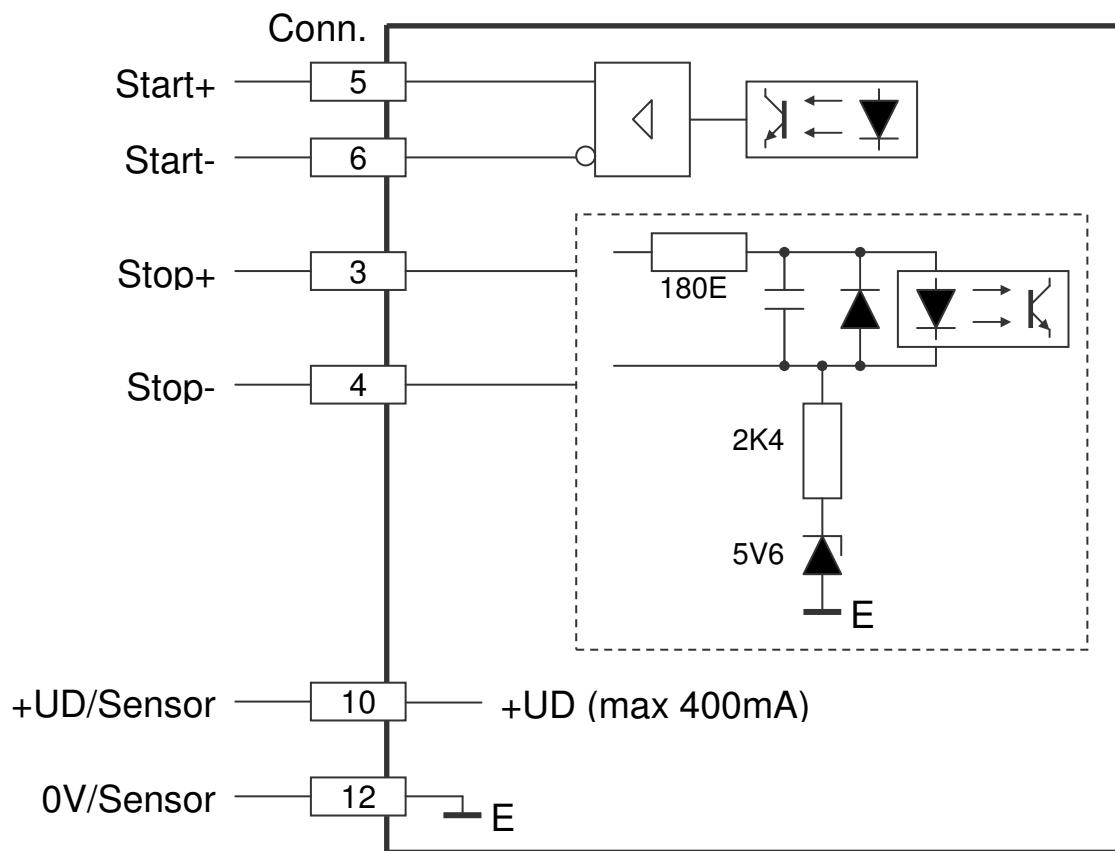
1. +10...+35V supply
2. 0V supply
3. Stop+
4. Stop-
5. Start+
6. Start-
7. Input-1
8. Input-2
9. common for inputs (0V)
10. +10...35V DC supply output for sensor
11. +5V DC supply output for sensor
12. 0V for sensor
13. TxD
14. RxD
15. Output -1
16. Output -2
17. Output -3
18. Output -4
19. 0V for outputs
20. +U for outputs

21. 0V analog
22. U-out
23. I-out

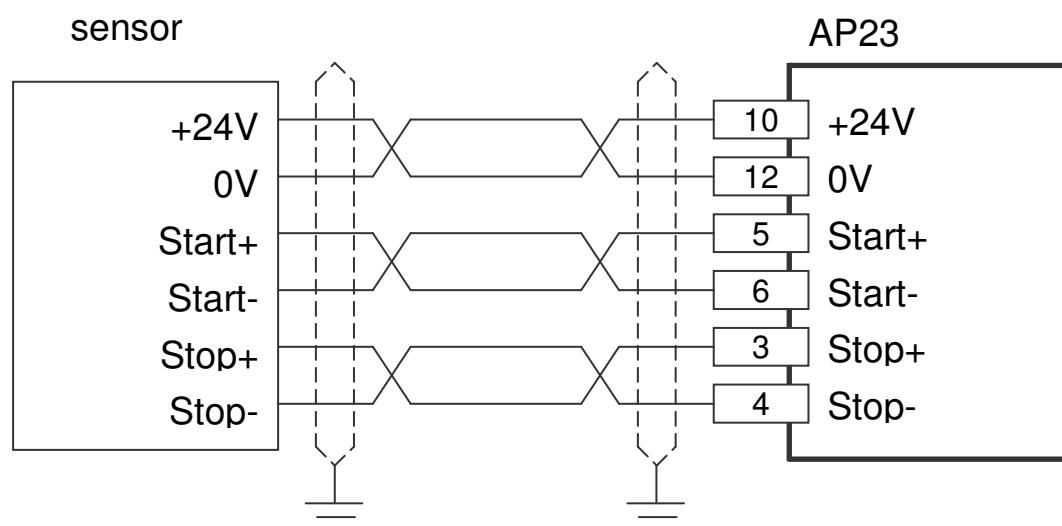
6.2 Supply



6.3 Start/Stop input

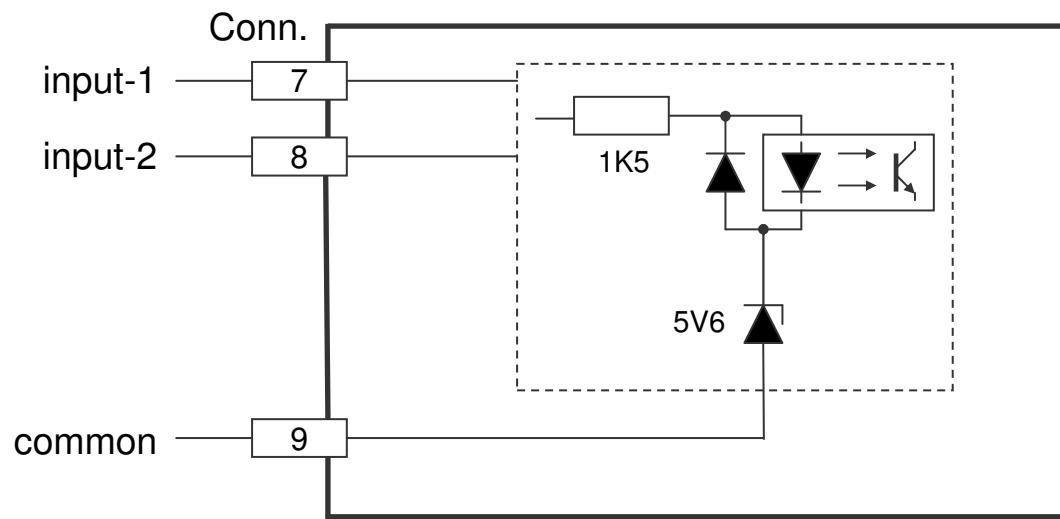


6.4 Start/Stop sensor 24V

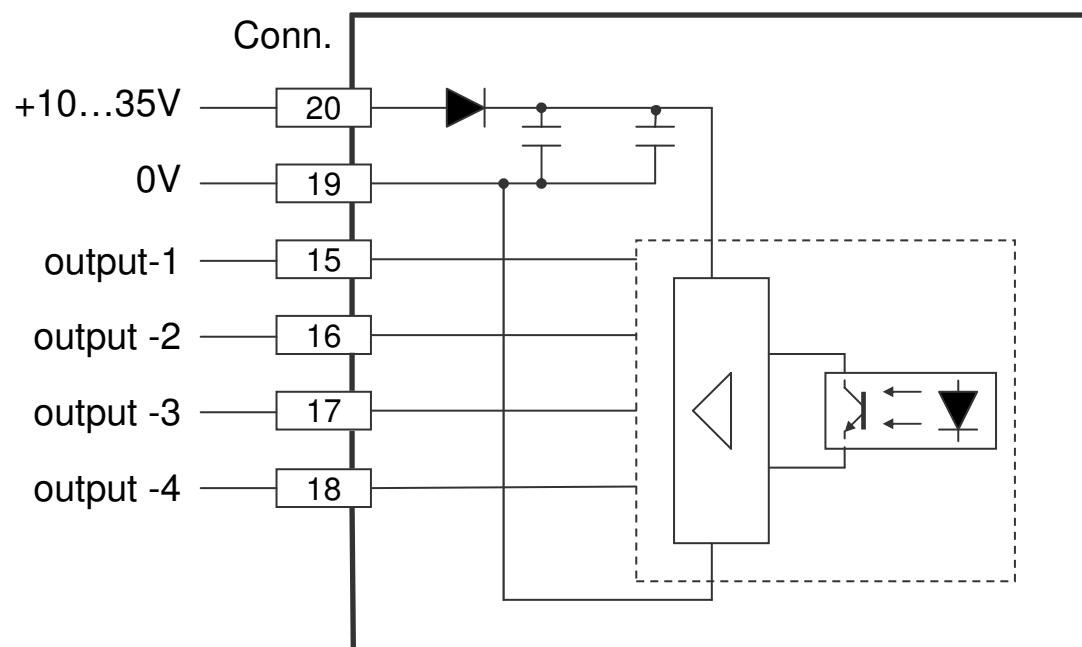


Supply voltage AP23 clamp 1 and 2 is 24V DC

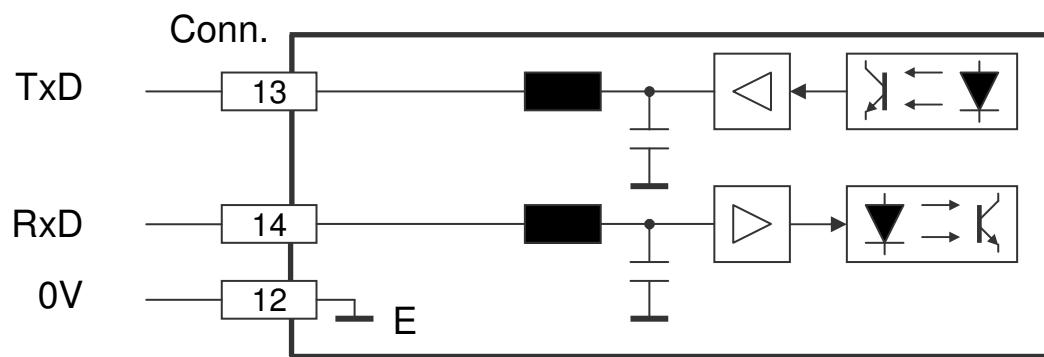
6.5 Digital inputs



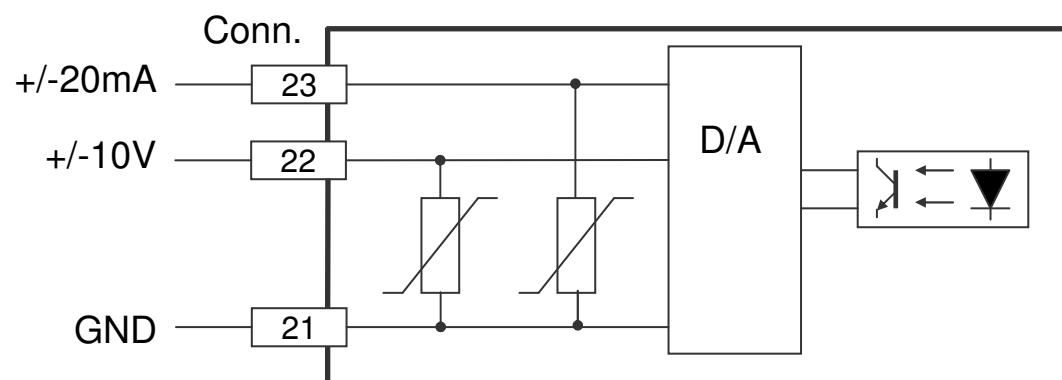
6.6 Digital outputs



6.7 RS232



6.8 Analog output



7 Technical specifications

7.1 Specifications

- Supply voltage	10...35V DC
current consumption	< 150mA
- Output voltage	for external encoder
+UD	max 400mA depending on supply voltage
+5V	max 400mA
- Processor	
μController	XC167
Data memory	EEPROM
Cycle time	250µS (fixed)
Counting range	-9999999...+9999999
- Start/Stop	optically isolated
stop-input	low 0...+0,8V
	high +2,8V...+5V
start-output	driver (RS422)
- Digital inputs 1...2	optically isolated
	low: 0...+5V
input resistor	high: +10V...+35V appr. 1.8kOhm at 24V
- Digital outputs 1...4	optically isolated, N FET, short-circuit proof
I _{max}	500 mA (min load 200 µA)
Supply voltage	35V max.
- Voltage output	galvanically isolated
range	max. -10V ... +10V
resolution	305 µV
offset-temp. coeff.	< 20 ppm/ °C
I _{max}	+/-12mA

Manual AP23 Start/Stop Display

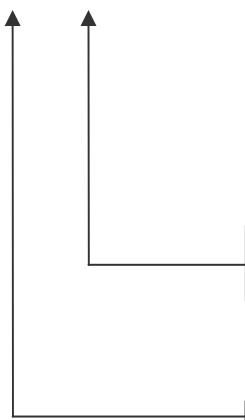
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- Current output	galvanically isolated
range	max. -20mA ... +20mA
resolution	610 µA
offset-temp. coeff.	< 20 ppm/ °C
Rmax	550 Ohm
- Serial communication	RS232 C
- Display	8 decades 7-segments LED
digit height	14 mm
- Temperature range	0...50 °C
- Connection diameter	1,6 mm ² (raster 3,81mm)
- Electromagnetic compatibility	in accordance with guideline
emission	2004/108/EC
immunity	NEN-EN-IEC61000-6-3:2007
- Weight	NEN-EN-IEC61000-6-3:2005
- Sealing	< 0.25 kg
	front IP50, with protective hood IP54
	rear IP20

7.2 Typekey

AP23- X X



Analog output

- 0 = no analog in- and output
- A = analog in- and output

Digital outputs

- 0 = no digital outputs
- D = 4 digital outputs

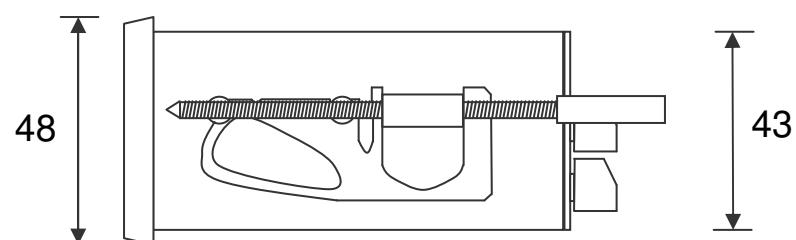
Manual AP23 Start/Stop Display

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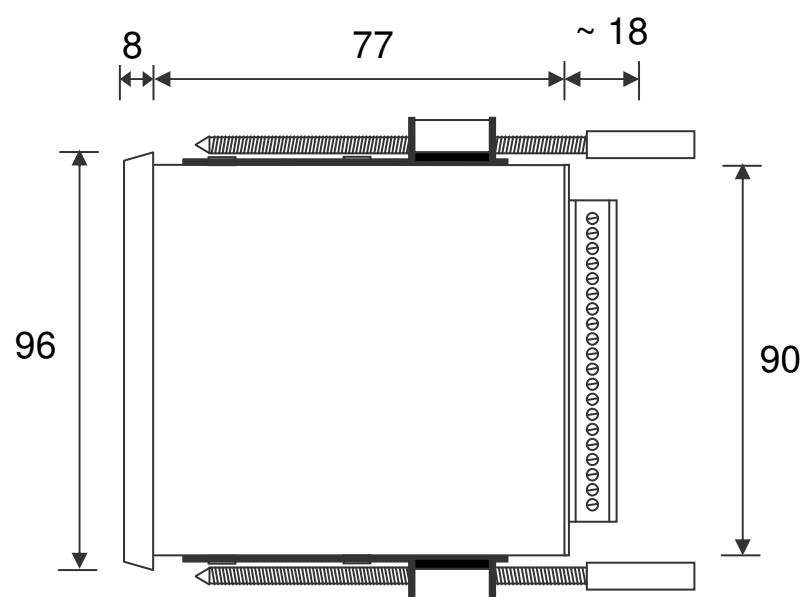
DIECON

7.3 Dimensions AP23

Side view

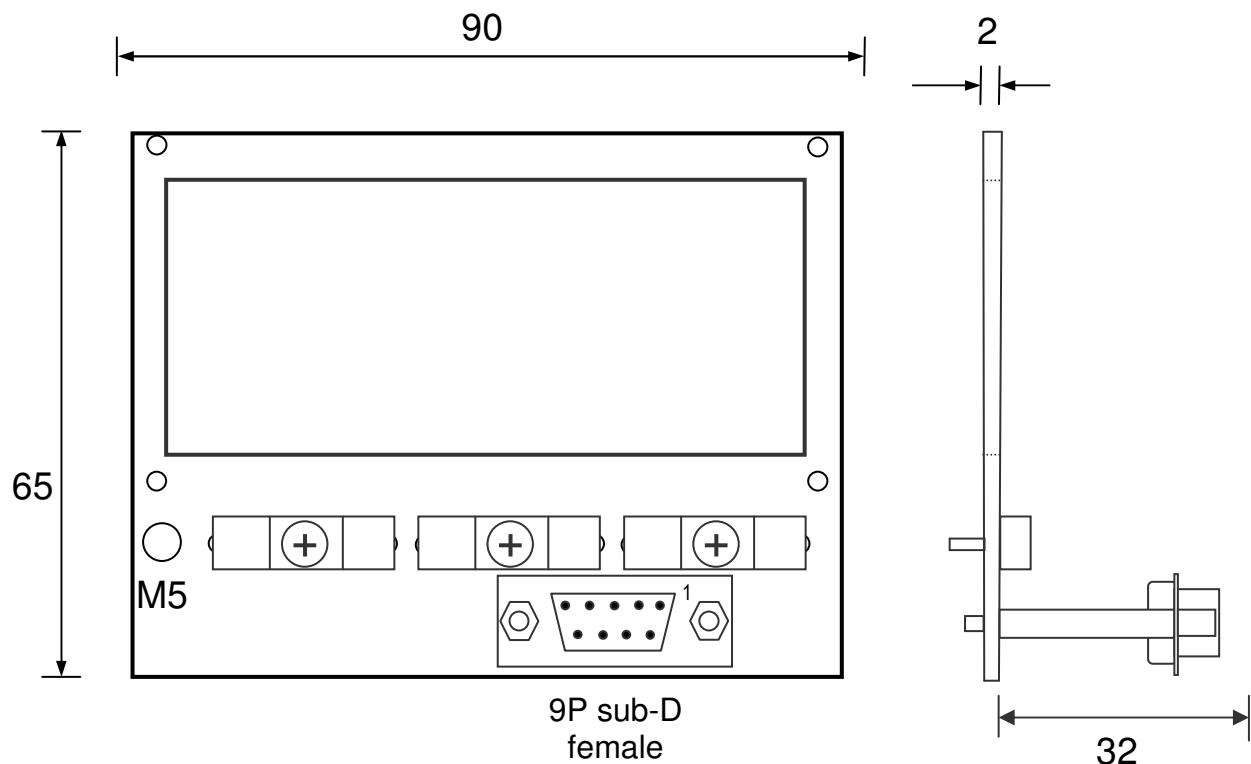


Top view

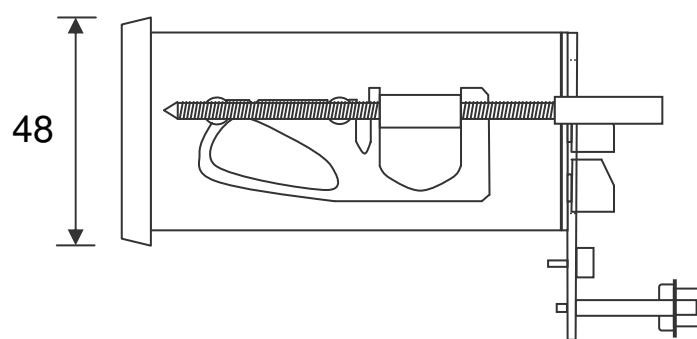


7.4 Dimensions EMC bracket type EMC-B02

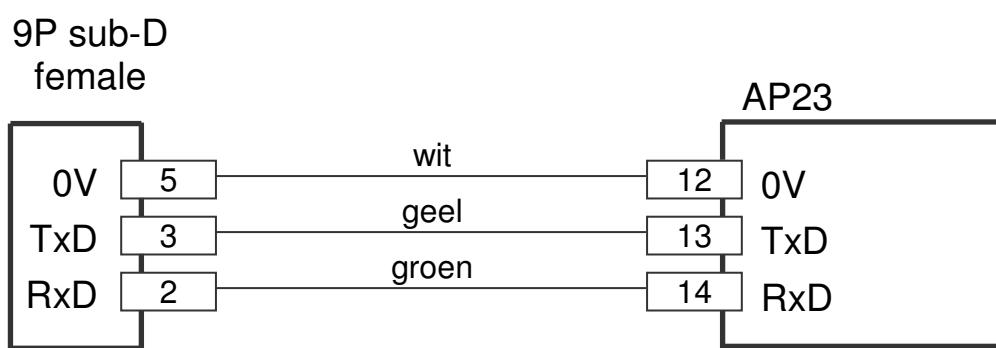
With RS232 (9P sub-D) on EMC bracket



Side view with EMC bracket



7.4.1 *Connections RS232 on 9P sub-D connector*



7.5 Dimensions protective hood type CDS-B02

